

S320 and SurvCE RTK Base Unknown Location

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Overview

This document describes how to configure the S320 RTK base using SurvCE at an unknown location, perform a "**Read from GPS**" to obtain a starting RTK base position, configure the S320 RTK rover to receive RTK corrections from the RTK base, outlines the procedures to perform a RTK Localization with SurvCE, and demonstrates how to store points with SurvCE and the S320 RTK rover. This quick reference guide outlines the procedures using S320's with the internal 400 MHz UHF radios.

Procedure

Screenshot or Graphic	Step
SurvCE Image: Constraint of the second	1. Turn on the XF1 data controller, start the SurvCE software. From the SurvCE main menu, Select File <u>1</u>Job
SurvCE Coordinate Files Image: CRD File	 2. Coordinates Files menu, A list of all the current jobs stored in the data controller are displayed, the last used job is selected by default. To create a new job, using the stylus, tap into the Name: template, the virtual keyboard will pop open,



Screenshot or Graphic	Step
SurvCE C 2:39 X Enter data X RTK-HERE Alphanumeric Special A B C D E F G H I J K L M N O P Q R S T U V W X Y Z abc 7 8 9 * + # ' 4 5 6 / - = " 1 2 3 Del Alt O Bk Sp Space	 3. Enter Data menu, Using the stylus, tap into the Enter Data template, using the virtual keyboard, enter a suitable name for the new job, in this example: RTK-HERE, Select/Tap , the virtual keyboard will close,
SurvCE Image: A ≤ 2:39 X Coordinate Files Image: A ≤ 2:39 X Type: CRD File	4. Coordinate Files menu, Type: CRD Files Name: RTK-HERE Select/Tap to create the new job,
SurvCE Image: Imag	 5. Job Settings System menu, Select the Distance units, Select the Angle preference, Last used Projection is displayed, To change the Projection, Select/Tap Edit Projection List,



Screenshot or Graphic	Step
SurvCE Image: A to	6. Coordinate Projection menu, Selection List: Recently used coordinate projections are listed, to select a different predefined coordinate projection. Select/tap, Add Predefined
SurvCE Image: Argent and Argent an	 7. Coordinate Projection menu, Country: USA/NAD83 Browse the list of coordinate projections, Select the appropriate state/zone for your projects location. In this example, FL East was selected, tap
SurvCE Image: Argent and Argen	8. Coordinate Projection menu, Selection List: USA/NAD83/FL East was added to the list, to use this coordinate projection, select USA/NAD83/FL East Then tap



Screenshot or Graphic	Step
SurvCE 2:40 X Sob Settings V X Format Options Stake New Job System Distance: Metric V Angle: Degrees, Minutes, Secc V Zero Azimuth Setting: North V Projection: Edit Projection List USA/NAD83/FL East V	9. The user is returned to, Job Settings System menu,
SurvCE Iob Settings New Job System Format Options Stake Use Control File Mome Time Stamp Each Point Store GPS Accuracy in Raw File Use Code Table for Description Recall Job Road Files Recall Job Localization Auto Load Map Auto Save Map Recall Image Database	 10. Job Settings Options menu Browse the list of available options, select the options as needed. For RTK surveys, select the options: √ Time Stamp Each Point √ Store GPS accuracy in Raw File. When all required options have been selected, Tap user is returned to the SurvCE main menu.
SurvCE Image: A ≤ 2:42 × Survey COGO Road File Equip 1 Total Station 6 Localization 2 GPS Base Image: Z Monitor/ 3 GPS Rover 8 Tolerances 4 GPS Utilities 9 Peripherals 5 Configure Image: Q About SurvCE	 11. The following steps outline the procedures to configure the S320 RTK Base. Setup up the S320 RTK Base over the survey point in the field; turn on the S320 GNSS receiver. Select Equip <u>2</u>GPS Base



Screenshot or Graphic	Step
Screenshot or Graphic	Step 12. GPS Base Current menu, Select the options, Manufacturer: Hemisphere GNSS Model: Eclipse II S320
SurvCE 2:42 X GPS Base X Current Comms Receiver RTK Type: Bluetooth X BT Type: Windows Mobili X Device: 5320 1841688 X	13. GPS Base Comms menu, Type: Bluetooth BT Type: Windows Mobile Device: S320 184xxxx Where the Device: S320184xxxx will be the actual serial number of your S320 Base.
SurvCE 2:43 X CPS Base X Current Comms Receiver RTK Type: Bluetooth BT Type: Windows Mobile X Device: S320 1841688 S S320 1841671 RC	 14. GPS Base Comms menu, From Device: using the stylus, tap the down arrow, select S320 184xxxx BASE; this will be the actual serial number of your S320 RTK Base. Select/Tap, I con to establish the Bluetooth connection between SurvCE and the S320 RTK Base. On the S320 RTK Base, the Bluetooth LED will be solid blue, indicating a successful connection.



Screenshot or Graphic	Step
Screenshot of Graphic	 Step 15. GPS Base Receiver menu, Select the HEMS320 antenna model, measure and enter the RTK Base antenna height. Select Vertical or Slant measurement type. If using a tripod/tribrach setup, select Slant. If using a 2-meter Fixed Height GPS tripod, select Vertical. For most all RTK surveys, the default Elevation Mask: 10, Position Rate: 1 Hz,
SurvCE C: Current Comms Receiver RTK Device: Internal nL400 Mic C Network: None Port: Parity: None Baud: J600 Stop: Message Type: ROX	 DGPS Type: None, DGPS Age Limit: 30 are acceptable. 16. GPS Base RTK menu, Device: Internal nL400 Microhard Message Type: ROX This is the default Hemisphere GNSS RTK message type. Other supported RTK message types options include: CMR and RTCMV3. To check the current UHF radio frequency, tap the isolated tools menu icon,
SurvCE	17. GPS Base RTK menu, Configure RTK Device Selecting Modem/Radio



Screenshot or Graphic	Step
💑 SurvCE 💦 🎝 ◀< 2:44 🗙	18. Configure Internal nL400 Microhard
Configemal nL40D Microhand	Power: 1 Watt (this is the max power setting for the internal radio).
	Current Frequency: 445.4500
Radio FW Version: v5.174-PC (MICROH Power: 1 Watt Frequency: 445.45000 Channel Spacing: 125442 Over the Air Baud: 9600	The user can enter the frequency, as permitted in their FCC Radio Station License. To change the frequency, using the virtual keyboard, manually enter the numerical frequency.
Radio Mode: PC1 (FEC On)	Select/Tap I to set the radio frequency.
🔧 SurvCE 🛛 🗱 🏠 📢 2:44 🛛 🗙	19. GPS Base RTK menu,
Current Comms Receiver RTK	Configuring Device
Device: Internal nL400 Micr	
Configuring device	
Cancel	
월 SurvCE 🛛 🗱 🏠 📢 2:45 🗙	20. Base Configuration menu,
Base Configuration X From Known Position From New Position	Two Base Configuration options are available:
	From Known Position
Read From GPS	From New Position
Enter Lat/Lon	In this example, the RTK Base is setup over an unknown location, the user does not know the GPS coordinates; select the option: From New Position,
Enter Grid System Coordinates	Then select the option:
	Read From GPS



Screenshot or Graphic	Step
💑 SurvCE 🛛 🚓 🏠 📢 2:46 🗙	21. Average GPS menu,
Average GP5	Available options are:
	By Number (of measurements),
By Time in min 3.000	By Time in Min
	Select the option you prefer, enter a suitable numerical value. In this example, By Time in Min option was selected, 3.000 minutes was entered.
GPS Monitor	Select/Tap I to start the Average GPS readings,
🄧 SurvCE 🛛 🗱 🏠 📢 2:49 🗙	22. Average GPS menu,
Average GP5	Taking Readings
Taking Reading #150 of 180 149 Valid readings recorded. Time remaining 0 min 31 sec.	In this example, By Time in Min option was selected, 3.000 minute duration was entered.
	Status of the Average GPS process is displayed to the user.
SATS:7/17 STATUS:AUTONOMOUS	
HSDV:2.328 VSDV:4.082	
Stop Averaging and Store	
🎭 SurvCE 🚓 🎦 📢 2:56 🗙	23. Base Configuration menu,
Base Configuration	Upon completion of the Average GPS process, the resulting Latitude, Longitude and Ellipsoid Hgt are displayed,
Broadcast ID: 1 Latitude: N 41°29'02.93796"	Enter a Broadcast ID: 1
Longitude: W 72°51'05.32443"	Continue with Base Setup?
Continue with Base Setup?	Select/Tap



Screenshot or Graphic	Step
SurvCE Image: Arrow of the second secon	24. Equip <u>2</u> GPS Base Configuring base Saving Configuration. Please wait
SurvCE Image: Survey	 25. Equip <u>2</u>GPS Base Base Configuration Successful. Save Settings to a File? Select/Tap Yes This option lets the user recall the RTK Base position at a later time, using the original Read from GPS position.
SurvCE Image: Station File Base Station File Image: REF File Image: Program Files\SurvCE\Data\ Backup BUFORD.ref	26. Base Station File Type: REF File Name: RTK-HERE By default, SurvCE will use the current job name, RTK-HERE.ref The user can change the name, but the .ref file extension must be used. Select/Tap



Screenshot or Graphic	Step
SurvCE SurvCE Survey COGO Road Eile Equip	27. This completes the S320 RTK Base setup. The user is returned to the SurvCE main menu.
1 Total Station 6 Localization 2 GPS Base 2 3 GPS Rover 7 8 Tolerances 7 4 GPS Utilities 9 Peripherals 5 Configure 9 Q About 1	On the S320 RTK Base, the UHF/GSM LED will be flashing red, indicating RTK Base data is being transmitted over the radio. The GPS LED will be solid yellow, indicating a valid position. The Battery LED's will indicated current battery condition, (both should be green), the flashing green LED indicates which battery is in use.
SurvCE Image: Argon and argon a	28. The following steps outline the steps to configure the S320 RTK Rover. From the SurvCE main menu, select: Equip <u>3</u> GPS Rover,
SurvCE Image: SurvCE GPS Rover Image: SurvCE GPS Rover Image: SurvCE Current Comms Receiver RTK Manufacturer: Hemisphere GPS Model: Eclipse II S320 Image: Load Save Bename Delete	29. GPS Rover Current menu, Select the options: Manufacturer: Hemisphere GNSS Model: Eclipse II S320



Screenshot or Graphic	Step
SurvCE A 3:02 X GPS Rover R X Current Comms Receiver RTK Type: Bluetooth V BT Type: Windows Mobili X Device: 5320 1841671 V	30. GPS Rover Comms menu, Type: Bluetooth BT Type: Windows Mobile Device: S320 184xxxx Where the Device: S320184xxxx, Will be the serial number of your S320 Rover.
SurvCE Image: Size x GPS Rover Image: X Current Comms Receiver RTK Type: Bluetooth BT Type: Windows Mobili Device: S320 1841671 S320 1841671 S320 1841671 S320 1841671 S320 1841671	 31. GPS Rover Comms menu, Device: using the stylus, tap the down arrow, select S320 184xxxx ROV, the actual serial number of your S320 RTK Rover. Select/Tap icon to establish the Bluetooth connection. On the S320 RTK Rover, the Bluetooth LED will be solid blue, indicating a successful connection.
SurvCE Image: SurvCe	 32. GPS Rover Receiver menu, Select the HEMS320 antenna model, Measure and enter the Rover antenna height. Typically, a fixed height 2-meter RTK survey pole is used. Select Vertical Antenna Height: 2.000 m For most RTK surveys, the default values for the Elevation Mask, Position Rate, DGPS Type: None and DGPS Age limit can be used.



Screenshot or Graphic	Step
SurvCE Image: Structure in the structure in	 33. GPS Rover RTK menu, Device: Internal nL400 Microhard √ Use Any Base Message Type: Auto To check/verify the UHF radio frequency, Tap the tools menu icon,
SurvCE Cancel	34. GPS Rover RTK Configure RTK Device A series of status messages are displayed to the user Retrieving settings
SurvCE Image: Angle	 35. Configure Internal nL400 Microhard radio Power: 1 Watt (this is the max power). Current Frequency: 445.4500 <u>Note:</u> this frequency MUST match the frequency set in the S320 RTK Base's internal radio. This enables the S320 RTK rover's internal radio to receive the RTK corrections from the S320 RTK Base. To set the Frequency, select/tap



Screenshot or Graphic	Step
SurvCE Current Comms Receiver RTK Device: Internal nL400 Micr X Configure RTK Device Configuring device Configuring device Cancel Senu Rover Position to Ivetwork SurvCE Current Comms Receiver RTK Device: Internal nL400 Micr X Network: Current Comms Receiver RTK	36. GPS Rover RTK menu, Configure RTK Device Configuring device Device Configured 37. User is returned to the GPS Rover RTK menu, To save all the GPS Rover configuration settings, Select/Tap
SurvCE Correct Common Receiver RTK Current Common Receiver RTK Device: Internal nL400 Micr X Configure RTK Device aving configuration. Please wait Cancel Send Rover Position to Network	 38. GPS Rover RTK menu, A series of SurvCE status messages are displayed to the user: Configuring Rover Selecting modem/radio Sending Data Configuring Rover Saving Configuration. Please wait Save Complete.



Screenshot or Graphic	Step
[#] SurvCE # ☆ ◀€ 10:10 × 愛JOB:RTK-HERE □ 1 1 10 10	39. The user is returned to the SurvCE main menu.
Survey COGO Road File Equip	This completes the steps to configure the S320 RTK Rover with SurvCE.
1 Total Station 🔢 6 Localization 🛄	On the S320 RTK Rover, Status LED's
2 GPS Base 7 Monitor/	UHF/GSM LED flashing Red = RTK Float
Skyplot	UHF/GSM LED flashing green = RTK Fix
4 GPS Utilities 💓 9 Peripherals 🔢	GPS LED solid yellow = valid GPS position
5 Configure 🛠 Q About 🔟	
💤 SurvCE 🚑 रें⊇ ◀< 3:04 🗙	40. To view the current RTK Rover status through SurvCE,
Survey COGO Road	Select Equip Monitor/Skyplot
Eile Equip	
1 Total Station 🔢 6 Localization 🔛	
2 GPS Base 🕱 Z Monitor/ 🕅	
3 GPS Rover 侯 8 Tolerances 👔	
4 GPS Utilities 💯 9 Peripherals 🔢	
5 Configure 🛠 Q About SurvCE	
💤 SurvCE 🚓 🎝 ◀< 3:04 🗙	41. Monitor / Skyplot Quality
Monitor/Skyplot SATView SATInfo Ref Quality Position	User can observe current RTK rover status: Fixed
Status: FIXED Age: 1.0 03/08/2012 Satellites: 12/17 15:03:58.0	Age of corrections, number of satellites being used, local coordinates, DOP's, horizontal and vertical RMS values.
Local Northing: 1934201.5501 Local Easting: 880770.7289 Local Elev: 30.5485 HDOP: 1.30 TDOP: N/A Reset VDOP: 2.00 GDOP: N/A RTK PDOP: 2.39 HRMS: 0.021 VRMS: 0.035	Status: Fixed is the best type of RTK solution available, the HRMS and VRMS values are an indication of the RTK position quality.



Screenshot or Graphic	Step
SurvCE Image: Arrow Sector (Skyplat) Monitor/Skyplat Image: Arrow Sector (Skyplat) SATView SATInfo Ref Quality Position Latitude: N 41°29'02.85843" Longitude: W 72°51'05.53969' Ellipsoid Elev: 30.5435 GEOID: No Geoid file loader Orthometric Elev: No Geoid file Localization File: None Local Elev: 30.5435 Local Elev: 30.5435 Local Northing: 1934201.5515 Local Easting: 880770.7382	42. Monitor/Skyplot Position User can observe the RTK Rover's Latitude, Longitude, Ellipsoid Elev, if a Geoid model file is loaded, Orthometric Elev will be displayed. Local Northing, Easting coordinate details.
SurvCE Image: SurvCE Image: SurvCE Image: SurvCE Quality Position Ref SATView SATInfo Ref Reference Station Coordinates Ref Longitude: W 72°51'05.32440" Ellipsoid Hgt: 32.3790 Store Store Distance to Ref: Antenna 5.596 m Antenna Antenna Type: 1.500 HEMS320 NONE Northing: 1934204.4829 Easting: 880775.5053 Elevation: 30.8547 Image: Suprove Supro	 43. Monitor/Skyplot Ref User can observe the Reference Station Coordinates details: Latitude, Longitude, and Ellipsoid Hgt. This is a good place to check/verify the RTK Rover is using the correct RTK Base position, the RTK rover radio is listening to your RTK Base. Distance to Ref: and RTK Base Antenna Type/Antenna HI details are displayed.
SurvCE	44. Monitor/Skyplot SATView Graphical Skyplot of the current RTK Rover GNSS satellites in view.



Screenshot or Graphic	Step
🀉 SurvCE 😂 🏠 📢 3:05 🗙	45. Monitor/Skyplot SATInfo
Wonitor/Skypiot Control Contro	Table view of current RTK Rover GNSS satellites in view.
PRN TY AZI ELV S/N • 1 GPS 0 0 0 0 0 0 0 0 0 0 0 0 0 0 11 GPS 48 14 0 11 GPS 299 9 0 12* GPS 72 35 48 = 10 12* GPS 72 35 48 = 10 11 10	PRN, Type of GNSS SV(GLN=Glonass), Azimuth, Elevation, S/N, (Signal to Noise).
14* GPS 322 53 45 18* GPS 147 32 45 22* GPS 186 73 50 25* GPS 124 40 49 31* GPS 228 34 47 32 GPS 314 5 0 42* GLN 132 35 44 43* GLN 19 81 51	Select/Tap to return to the main menu,
Survey COGO Road File Equip 1 Total Station for the formula station station for the formula station for the formula station	46. Since the RTK Base used an Unknown GPS position, the RTK Rover MUST localize, Equip Localization
	Localization is a process that allows the user to shift the GPS measurements to a local coordinate system. Localization can be used to improve the local fit of your national coordinate system, (so your survey fits the local control), or to create a completely arbitrary coordinate system, (with new origin and axes).
	To adjust to local control: The RTK Rover must have a Fixed RTK Solution when observing the control points. Typically, the RTK Rover occupies a single, or multiple control points, storing the RTK Fixed GPS coordinates, associating the GPS coordinates to the local coordinate values.
🧞 SurvCE 🚓 🎦 📢 5:26 🗙	47. Localization System
Points By Helmert System TS Opjection: Edit Projection List USA/NADB3/FL East Image: Convert WGS84 to NAD83	Displays the current projection, selected when the job was created.



Screenshot or Graphic	Step
🧏 SurvCE 🚓 🍋 ┥🤆 S:27 🗙	48. Localization GPS menu,
😂 Localization 🛛 🔀	Localization Method
System TS GPS	Multiple Point Method: Plane Similarity
Base Translation	One Point Azimuth: State Plane Grid
Multi Point Method: Pane Sim Janoy One Point Azimuth: State Plane Gi	If the local control points are State Plane coordinates, and you want RTK derived Orthometric heights, you must attach a Geoid model to the Projection. To attach a Geoid Model,
Grid to Ground:	Select/Tap Geoid File:
🎭 SurvCE 🚑 🎦 📢 6:18 🗙	49. Geoid Separation File menu,
Geoid Separation File	Type: GSF File
Type: GSF File V V V V V V V V V V V V V V V V V V V	The GSF File is created on the office PC using the Carlson XPort utility S/w. The GSF File is a small manageable sized file that contains the Geoidal separations that encompass the project site. After the GSF file is created, it is copied to data controller's \Program Files\SurvCE\Data\ folder.
Name:	The GSF file gets attached to the coordinate projection, enabling Orthometric elevations to be computed and stored with the point coordinates. If a GSF file is not attached to the Projection, only Ellipsoid Heights will be computed.
	After selecting a GSF File, Select/tap
2 SurvCE # 23 4€ 11:02 ×	50. Localization Points menu,
System TS GPS Points By Helmert	Typical field procedure, the S320 RTK Rover occupies the local control point, selects/Tap ADD .
Pt ID Northing Easting Eleva	The local control point coordinates must be previously stored in the current Job's coordinate file before the RTK Rover can occupy the control points for Localization. The user cannot add control points using the Add button. ADD is the occupy function of the Localization process.
Add Delete Edit On/Off Load View Monitor Save	To add control points/coordinates to the job, exit from the Localization menu, From the main menu, select <u>1</u>File <u>3</u>Points



Screenshot or Graphic	Step
SurvCE Image: SurvCE Survey COGO Road File Equip 1 Job 6 Data Transfer 2 Job Settings 7 Import/ 8 Delete Job 4 Raw Data 9 Write Note 5 Feature Code 0 Exit	51. To add control points to the current job, so they can used for the Localization, Select File <u>3</u> Points menu,
SurvCE Image: Constraint of the second s	52. From the File <u>3</u>Points menu, Select/Tap <u>Add</u> ,
SurvCE Image: Add Point Add Point Image: Add Point Image: Point ID: 6402 Northing: 233593.0010 Image: Point ID: 6402 Northing: 233593.0010 Image: Point ID: 6402 Image: Point ID: Add Notes Image: Image: Point ID: Add Notes	 53. Add Point menu, Using the stylus, tap into the Point ID template, the virtual keyboard will pop open, Enter the Point ID, Northing, Easting, Elevation, and Description for the control point, To store the Point, select/tap



Screenshot or Graphic	Step
SurvCE Image: Constraint of the second s	 54. From the File <u>3</u>.Points menu, If you need to add additional control points, select/Tap <u>Add</u>, After entering all the control points required to the current job, select/tap , user is returned to the main menu, The user can return to the Equip Localization menu, resume the Localization process.
SurvCE Image: Survey	55. From the main menu, select Equip Localization,
SurvCE	 56. Return to the Localization Points menu, The S320 RTK Rover occupies the local control point, When ready, tap the Add button,



Screenshot or Graphic	Step
SurvCE Image: S:27 X Image: Local Point Image: S:27 X Please enter local coordinate values. You may use a point ID from the current or control job. Image: SurvCE Point From File: Image: SurvCE Image: SurvCE Local Northing: Image: SurvCE Image: SurvCE Local Easting: Image: SurvCE Image: SurvCE Local Elevation: Image: SurvCE Image: SurvCE	57. Local Point menu, Select/Tap the points icon,
SurvCE Image: A ≤ 1:04 × Point Details Image: A ≤ 1:04 × Point ID Northing Easting Ele 1 1934201.54 880770.74 30. 2 1934204.48 880775.51 30. 6402 233593.00 295810.70 11.	 58. Point Details menu, Select the Point ID of the local control point to be physically occupied by the RTK Rover, to be included in the Localization. Select/Tap Select/Tap
SurvCE Image: Amage: Amage	59. Local Point menu, When ready to start taking RTK observations on the Local Point (2), Select/Tap







Screenshot or Graphic	Step
SurvCE	63. Typically, after storing the first control point in the localization process, the RTK Rover moves to the next control point, occupies the point, plumb and levels the RTK Pole, select/taps Add, selects the Point ID of the control point, Selects Read From GPS. Typically, 3-5 control points are occupied during the Localization process. After a sufficient number of control points have been occupied, select Save the localization results can be reviewed, suspicious points can be toggled On/Off, bad control points can be Deleted . If making changes to the Localization, be sure to Save . This completes the overview of the Localization. For addition details on Localization, refer to the SurvCE manual. Select/Tap to exit the Localization menu.
SurvCE Image: Survey and Surve	64. After successfully completing the Localization process, the user can Store Points, Stake Points, etc. To Store Points, Select, Survey <u>1</u>Store Points



Screenshot or Graphic	Step
💤 SurvCE 🛛 🗱 🏹 📢 3:07 🗙	65. Store Points menu,
SIA C M Fixed I+I13/17 30 m I	Before storing points with the S320 RTK Rover, enter a starting PT: number, enter a suitable description, enter/confirm the RTK Rover Antenna Height.
Pt: 10 Desc: Topo PT HT: 2 N:1934201.5474E:880770.7282 Z:30.5215	The RTK rover should have a Fixed RTK solution, observe the HSDV and VSDV values, when ready to Store the Point, Plumb and level the RTK antenna/pole over the point of interest,
HSDV:0.012 VSDV:0.016	Select/Tap (), to store the point,
デョ SurvCE # 谷 ◀< 3:08 ×	66. If the user configured the Averaging
	settings in Average GPS Menu
Taking Reading #2 of 5 1 Valid readings recorded.	The user will observe the Taking Reading status. Upon the completion of the 5 readings, the point will auto store.
SD.North: 0.0000	
SD.East: 0.0000 SD.Elev: 0.0000 SATS:13/17 STATUS:FIXED	Continue storing points as needed.
HSDV:0.012 VSDV:0.018	
Stop Averaging and Store Cancel Averaging	
🎭 SurvCE 📰 🏹 📢 2:28 🗙	67. When the user has completed the RTK
Survey COGO Road	survey, return to the main menu,
Equip	Select File <u>0</u> Exit
1 Job 🗳 6 Data Transfer	
2 Job Settings 😜 Z Import/ 🕒	Are you sure you want to exit?
3 Points 1 Belete Job	Yes No.
4 Raw Data 🔯 9 Write Note 🥓	Tes No
5 Feature Code D Exit	Select Yes

Further Information

The Precision Products Technical Support team in Scottsdale has coordinated defining these Quick Reference Guides. You can contact Precision Products Technical Support at techsupport@hemispheregnss.com for further information.

For additional information on SurvCE, please visit the Carlson SurvCE web site at:

www.survce.com

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